Amendments to the Specification

Please amend the paragraph beginning at page 14, line 9, as follows;

When (θ) is defined as an angle of a line connecting between the farthest point (P) and the center (O) of the trunnion 8, relative to the trunnion centerline (Q), the angle (θ) is set to be $5° < (\theta)$. Thus, a relatively large spherical outer surface area of the trunnion 8 is provided for receiving a load applying onto the outer surface of the trunnion 8. Accordingly, a contact surface area for receiving the load is increased, thereby enabling contact stress to be dispersed. The cylindrical face 13 formed on the trunnion 8 <u>does not intersect</u> ~~is spaced from~~ the contact surface area on each trunnion 8. As such, the contact surface area receives the load during rotation of the joint 1.